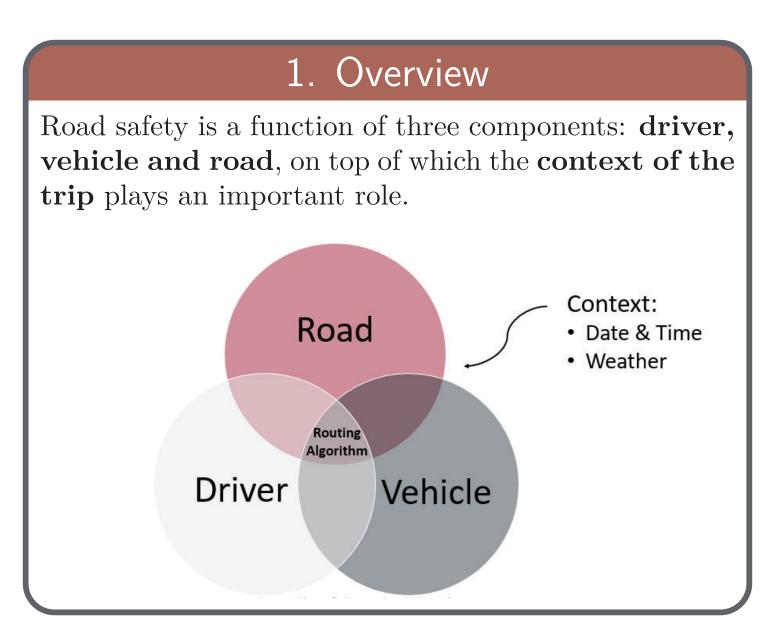


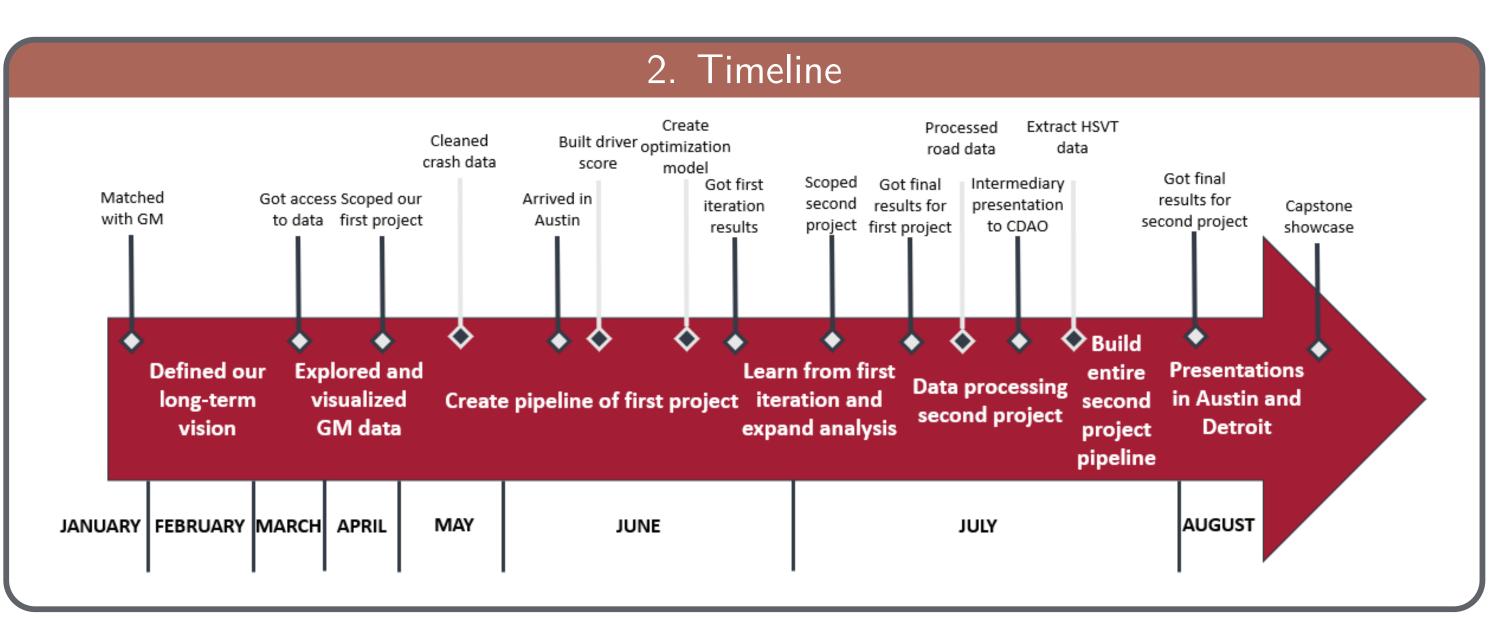
Zero Crashes Initiative

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3. First product goal

To explain crashes, our first goal is to understand how a given vehicle or behavior feature impacts safety. Therefore, we built a reproducible framework that quantifies the real effect of any feature on safety, which relies on three main data sources:

Data type	Size
Vehicle data	5.2M
Trip characteristics data	8.3B
Severe crashes data	37K

We have identified and rigorously removed three biases: the **vehicle characteristics**, the driving time and the driving behavior.

4. Driver score method comparison

To tackle the **driving behavior** bias, we built a **driver score**, derived from predicted crash likelihood. Below are the testing AUC for combinations of resampling and modeling techniques:

	Re-sampling techniques		
Modeling	Over-sampling	\mathbf{SMOTE}^1	$\mathbf{SMOTEEN}^2$
Logistic Regression	0.727	0.730	0.722
FFNN (Neural Network)	0.752	0.722	0.723
CART	0.699	0.689	0.667
Random Forest	0.782	0.738	0.688

1 = Synthetic minority over-sampling technique

2 = Combine over- and under-sampling using SMOTE and edited nearest neighbours

5. Bias removal techniques

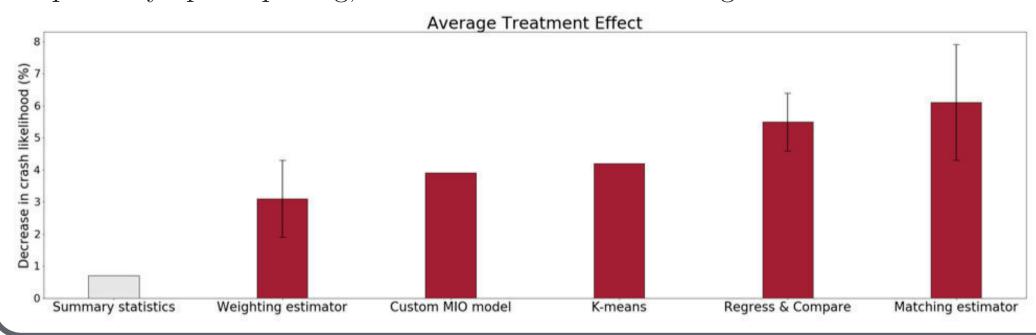
In order to analyze the unbiased effect of a given feature on safety, we create groups of similar drivers and compare treated and untreated drivers in each group, using the following techniques:

- K-Means clustering to gather similar drivers together,
- Causal inference estimates to simulate a randomized experiment,
- A custom **mixed-integer optimization** model:

proportion discrepancies between treated and untreated drivers driver assignment categorical groups to groups features

6. Results & impact

We applied our framework to uncover the real effect of the **forward collision alert** safety option. Customers, GM and insurance companies, which can better adapt safety option pricing, can benefit from such findings.



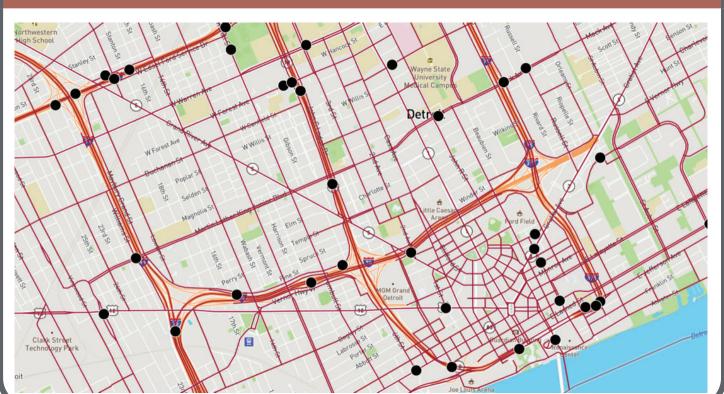
7. Second project goal

To deepen our understanding of crashes, we built a **road** risk score. Since GM does not store road data, we web-scraped open data about the Detroit area:

Data source	Size
Road features	20K road segments
Road geometry	260K road segments
Intersections	98K intersections

We split roads into segments, extracted features about them and matched crashes to those segments.

8. Crash locations matching

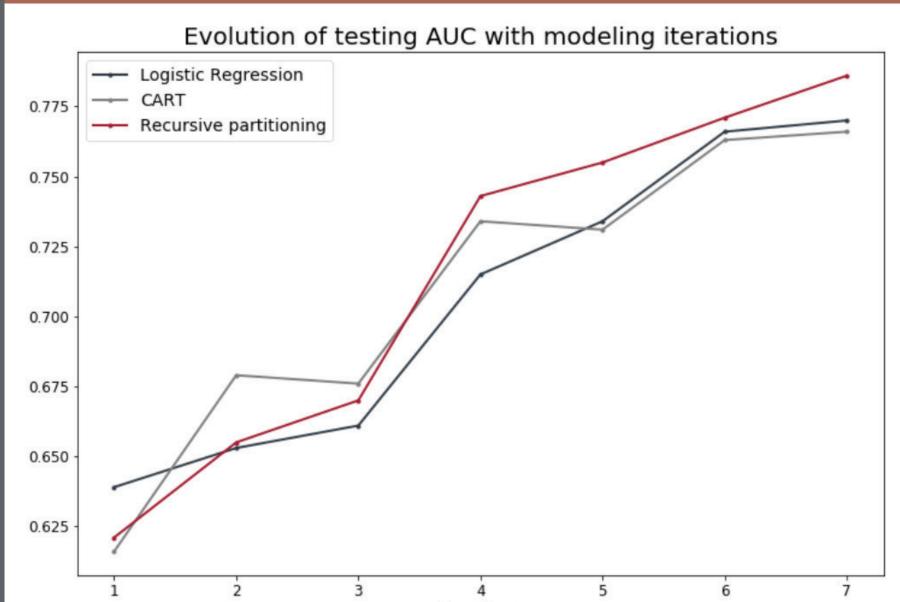


9. Road risk score impact

Our road risk score can be impactful in many ways:

- Enhance safety awareness and strengthen GM's position as a safety leader using interpretable coefficients
- Help city-planners decide which road to renovate and how
- Partner with insurance companies to reduce number of crashes by incentivizing their customers to take safer routes

10. Predictive power comparison & evolution



Iterations

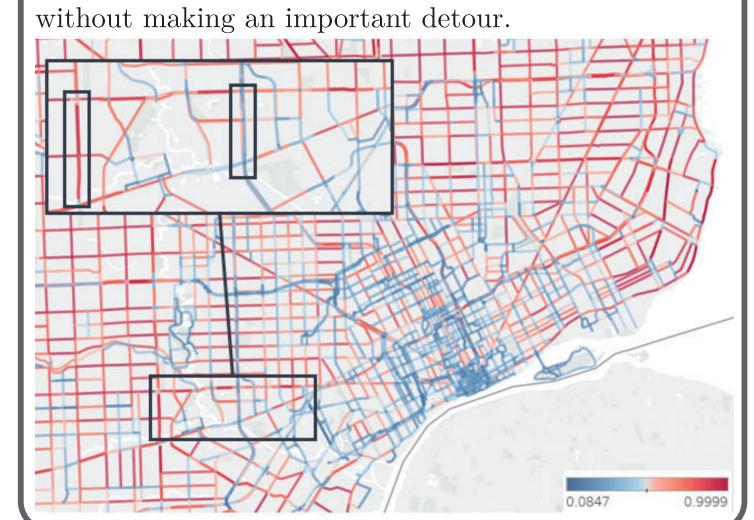
- **Step 1**: Raw features only
- Step 2: Feature engineering (binning) and spatial data imputation
- Step 3: Add interactions between features
- Step 4: Process intersection data
- Step 5: Feature engineering: road angle
- Step 6: Process GM telemetry data
- Step 7: Resample the training data

Subset of features	Logistic Regression coefficients	
Traffic volume	0.830	
Number of intersections	0.576	
without traffic signal		
Pavement type asphalt	0.278	
Number of intersections	0.200	
with traffic signal	0.200	

11. Re-routing to safer routes

The plot of Detroit's road risk score shows **consistency** from a segment to the next one.

Moreover, it is often possible to find a safer route



Conclusion and recommended next steps

We investigated the driver, vehicle and road's impact on safety and potential use cases.

For the first project, we recommend to apply our framework to find the real effect of weather and the effect of loud radio volume on safety.

GM should also start engaging insurance companies with both projects to reduce crashes and monetize its data. In particular, our first product can help insurance companies adapt safety option pricing, while our road risk score product can be turned into a white-label app and used to incentivize customers to take safer routes. To achieve the zero crashes goal, GM should build a personalized road risk score that would lead to the safest routing algorithm: first, find features that are relevant to safety using our first product's framework, then incorporate them into our second product's risk score model that would be unique to a driver in a given vehicle.